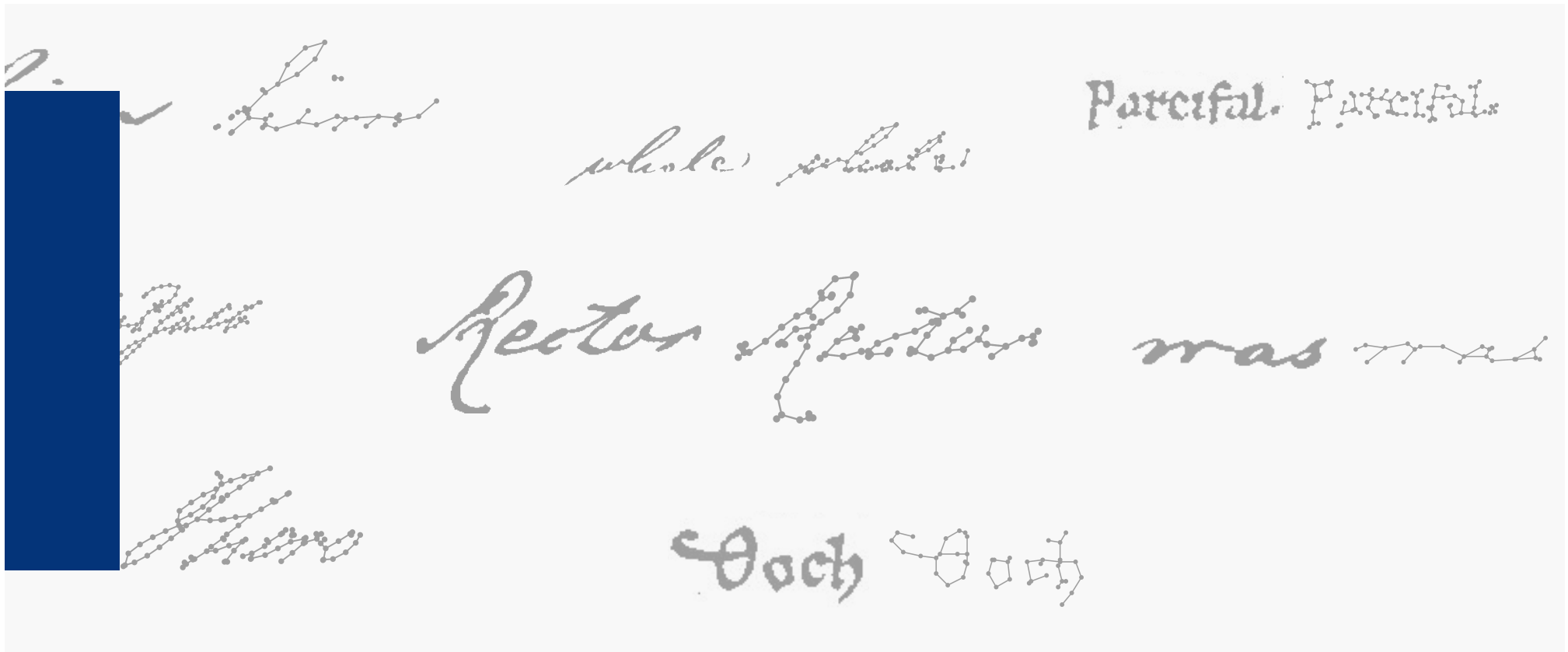


DAS 2018

Graph-Based Keyword Spotting in Historical Documents Using Context-Aware Hausdorff Edit Distance

Michael Stauffer, Andreas Fischer, and Kaspar Riesen

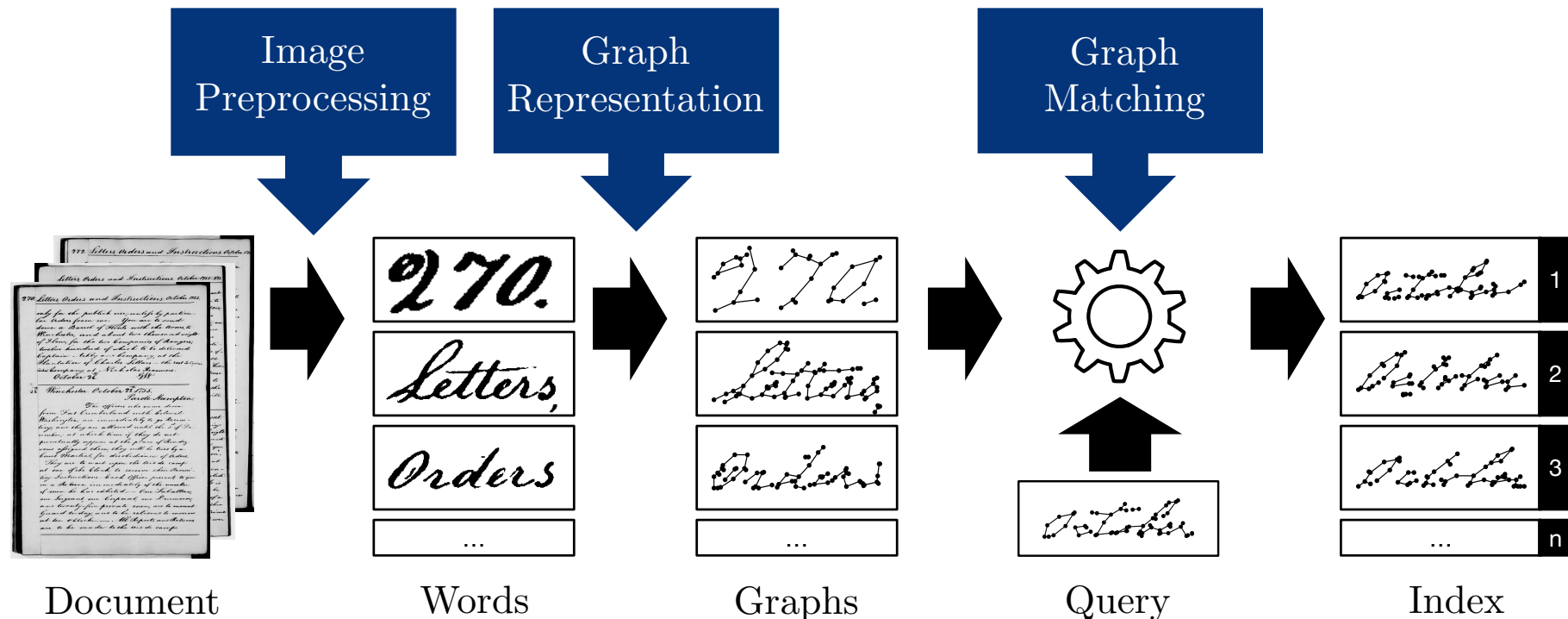


Content

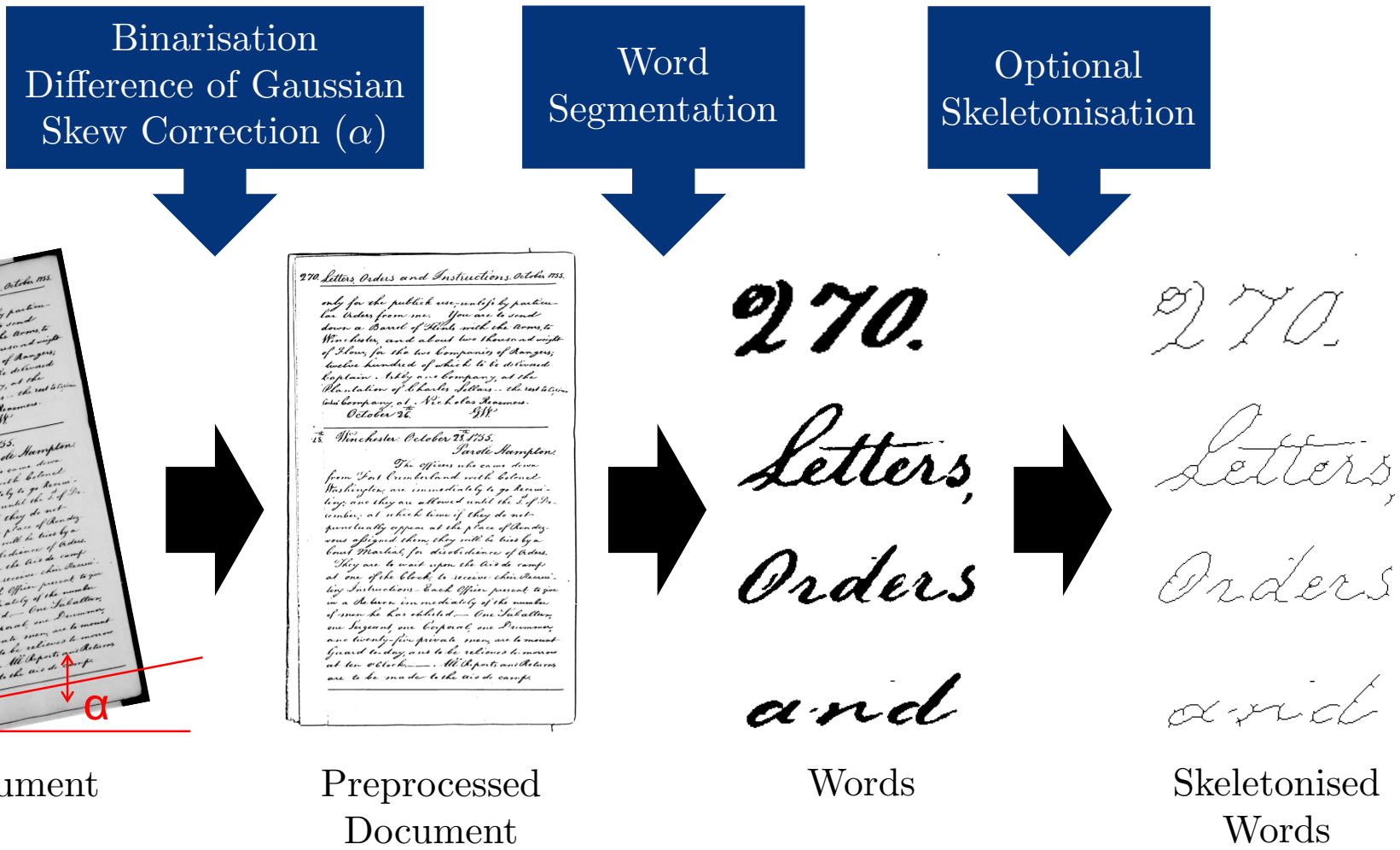
- Graph-based Keyword Spotting
 - Image Preprocessing
 - Graph Representation
 - Graph Matching
 - Graph Edit Distance
 - Context-Aware Hausdorff Edit Distance
 - Ensemble Methods
- Experiments
- Conclusion
- Q+A

Graph-based Keyword Spotting (KWS) – Overview

Graph-based KWS is based on the **representation** of words by means of different graphs. This representations are eventually used to **retrieve** a keyword by **matching** a query graph with all document graphs.



Graph-based Keyword Spotting – Image Preprocessing



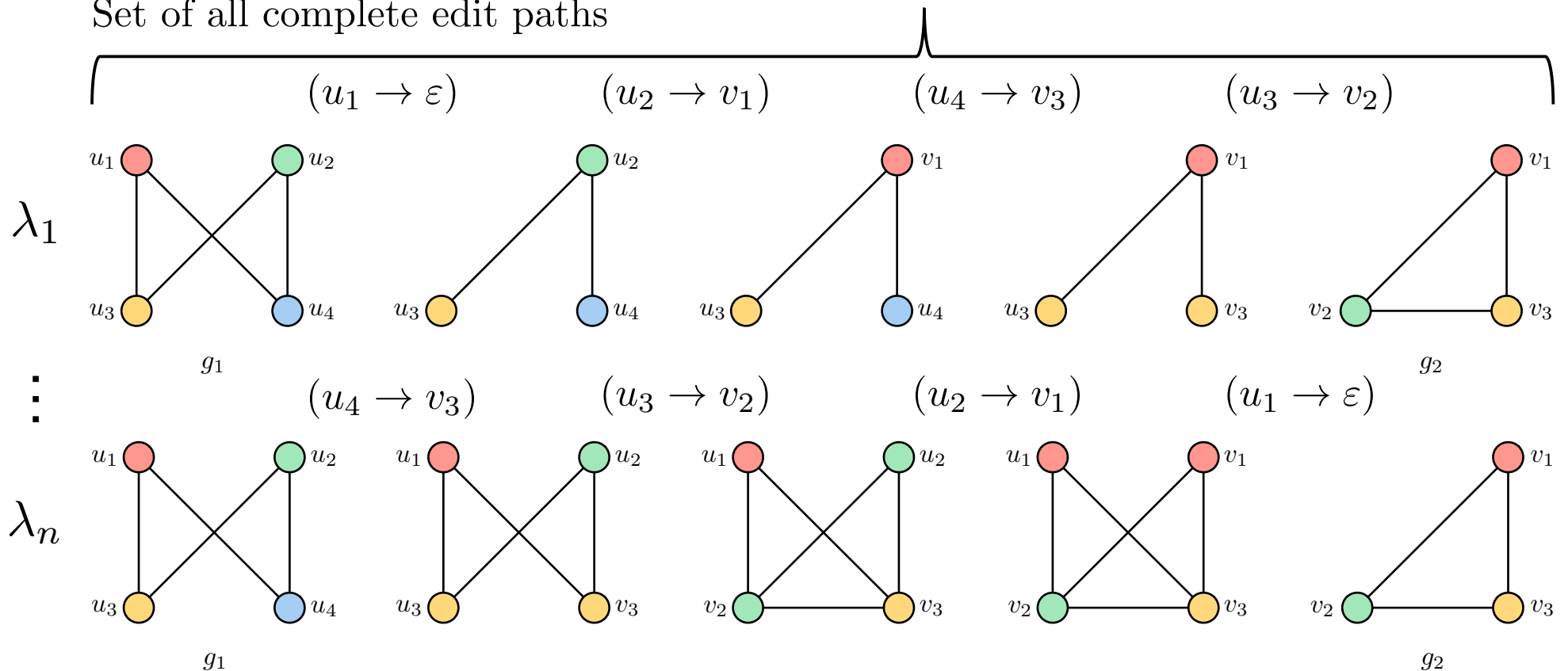
Graph-based Keyword Spotting – Graph Representation

	Original	Preprocessed	Keypoint	Projection
George Washington				
Parzival				
Alvermann Konzilsprotokolle				
Botany				

Graph-based Keyword Spotting – Graph Edit Distance (GED)

$$d_{\text{GED}}(g_1, g_2) = \min_{\lambda \in \Upsilon(g_1, g_2)} \sum_{e_i \in \lambda} c(e_i)$$

Set of all complete edit paths

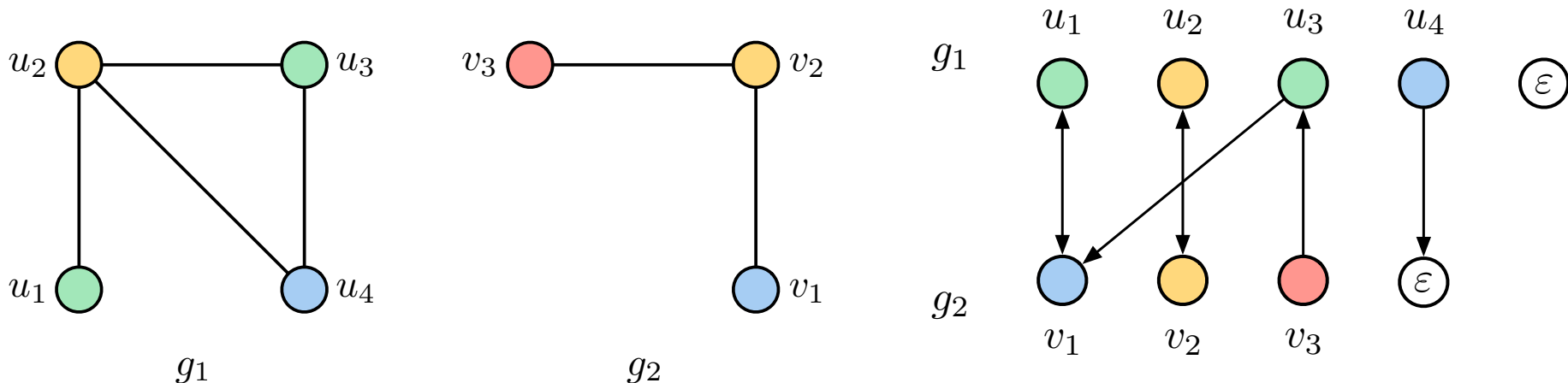


Graph-based Keyword Spotting – Hausdorff Edit Distance (HED)

The number of edit path is exponential, and thus, HED reduces the problem of GED to a set matching problem between local substructures.

$$d_{\text{HED}}(g_1, g_2) = \sum_{u \in V_1} \min_{v \in V_2 \cup \{\epsilon\}} h(u, v) + \sum_{v \in V_2} \min_{u \in V_1 \cup \{\epsilon\}} h(u, v)$$

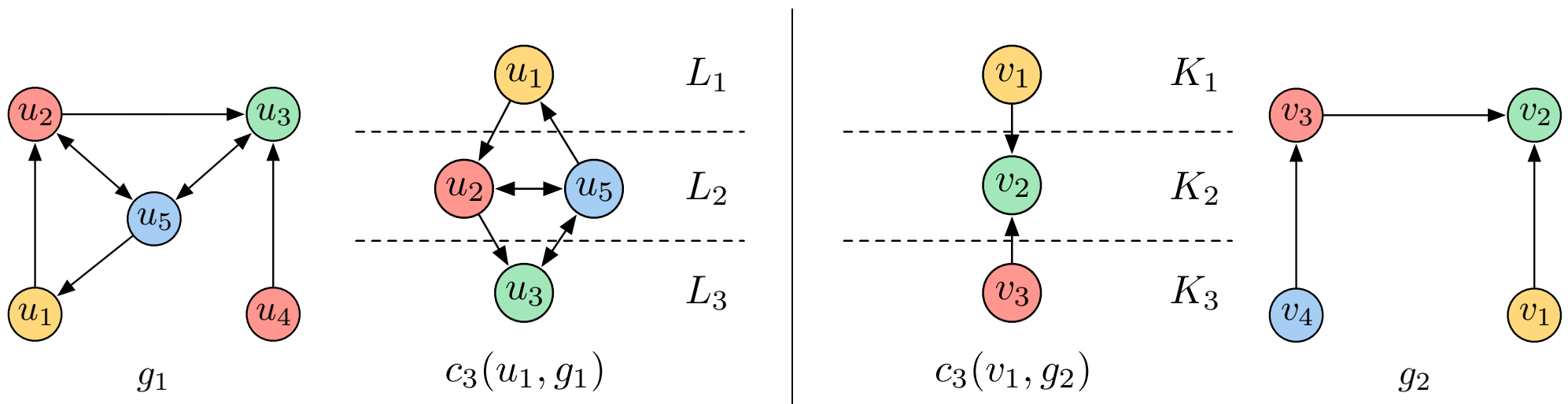
where $h(u, v)$ is the assignment cost of nodes and adjacent edges.



Graph-based Keyword Spotting – Context-Aware Hausdorff Edit Distance (CED)

How dissimilar/similar is graph context $c_3(u_1, g_1)$ and $c_3(v_1, g_2)$?

$$d(c_n(u, g_1), c_n(v, g_2)) = \sum_{i=1}^n d_{HED}(L_i, K_i)$$

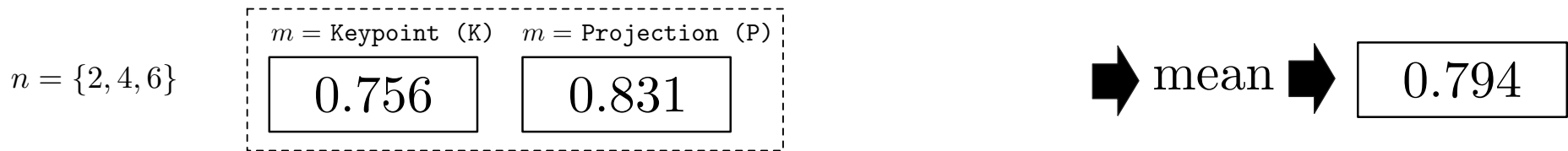


$$d_{CED}(g_1, g_2, n) = \sum_{u \in V_1} \min_{v \in \{b_n(u, g_2), \epsilon\}} h(u, v) + \sum_{v \in V_2} \min_{u \in \{b_n(v, g_1), \epsilon\}} h(u, v) ,$$

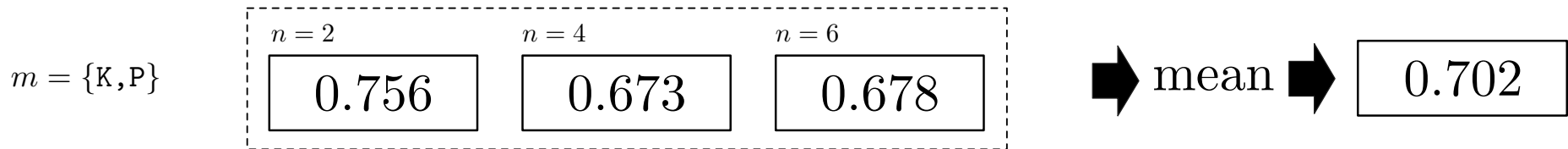
where b_n is the node in g_1/g_2 with minimum structural node context distance.

Graph-based Keyword Spotting – Ensemble Methods

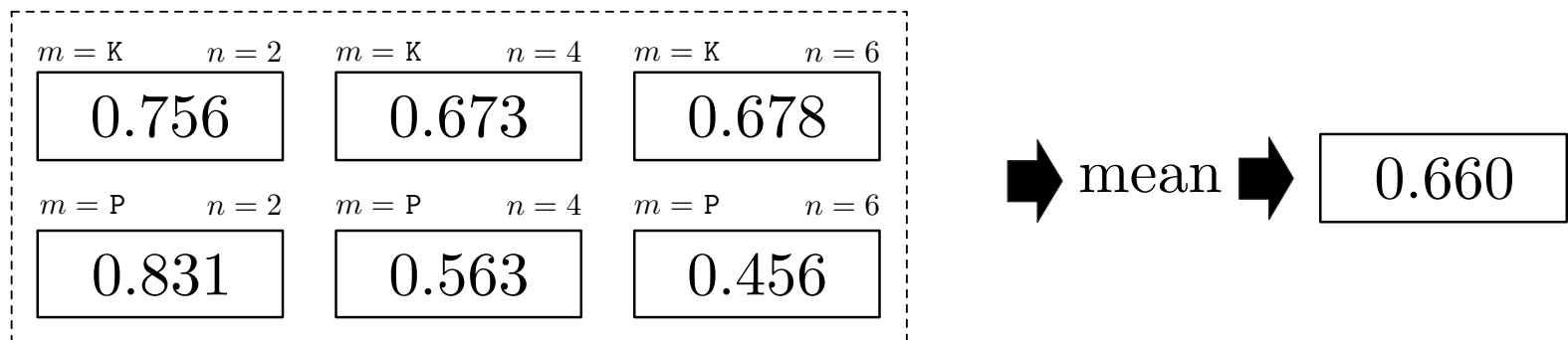
mean-Graph(n)



mean-Context(m)

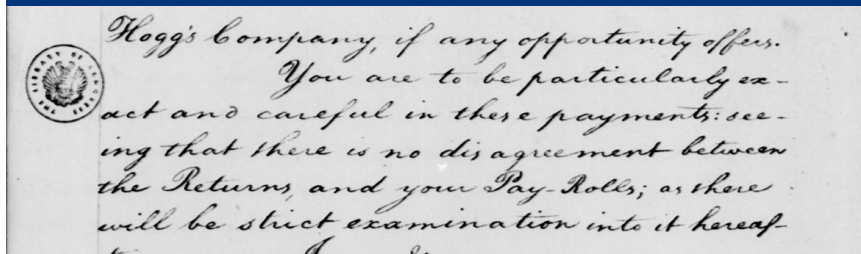


mean-All



Experiments – Datasets

George Washington (GW)

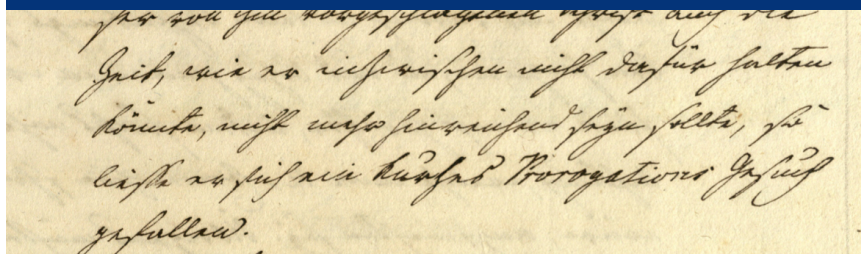


Parzival (PAR)

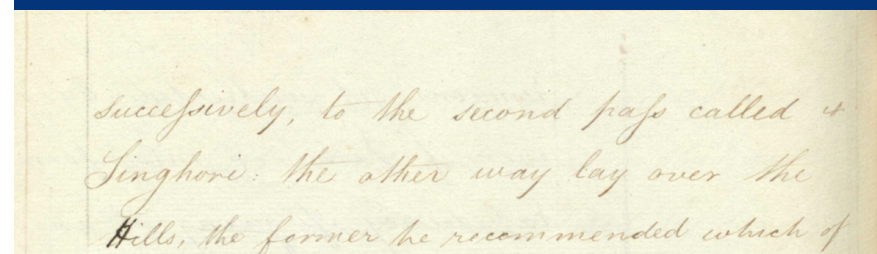


Graph-based vs. template-based KWS

Alvermann Konzilsprotokolle (AK)



Botany (BOT)



Graph-based vs. learning-based KWS

Experiments – Results Graph-based KWS Methods (Accuracy)

Bipartite Graph Edit Distance (BP) vs. Hausdorff Edit Distance (HED) and Context-Aware Hausdorff Edit Distance (CED).

Method		GW		PAR		BOT		AK	
		MAP	±	MAP	±	MAP	±	MAP	±
BP	Keypoint	66.08		62.04		45.06		77.24	
	Projection	61.43		66.23		49.57		76.02	
HED	Keypoint	69.28	+3.19	69.23	+7.19	51.74	+6.68	79.72	+2.48
	Projection	66.71	+5.28	72.82	+6.59	51.69	+2.12	81.06	+5.04
CED ($n = 2$)	Keypoint	71.23	+5.15	68.39	+6.35	51.59	+6.53	80.73	+3.49
	Projection	67.04	+5.62	74.10	+7.87	51.98	+2.41	80.28	+4.26
CED ($n = 4$)	Keypoint	68.46	+2.37	68.64	+6.60	52.18	+7.12	81.43	+4.19
	Projection	64.51	+3.08	73.99	+7.76	52.02	+2.45	82.42	+6.40
CED ($n = 6$)	Keypoint	65.23	-0.85	67.19	+5.15	52.45	+7.39	82.69	+5.45
	Projection	60.25	-1.18	72.45	+6.22	50.59	+1.02	81.58	+5.56

Accuracy is measured by Mean Average Precision

Experiments – Results Graph-based KWS Methods (Time)

Average matching time (ms) per graph pair using BP with cubic time complexity, and HED and CED with quadratic time complexity.

Method	GW	Speed-Up	PAR	Speed-Up	Average	Speed-Up
BP	303.0		437.5		370.3	
HED	3.2	x 95	5.2	x 84	4.2	x 88
CED ($n = 2$)	7.5	x 40	12.5	x 35	10.0	x 37
CED ($n = 4$)	14.6	x 21	20.1	x 22	17.4	x 21
CED ($n = 6$)	17.5	x 17	30.4	x 14	23.9	x 15

Experiments – Results Graph-based vs. Template-based KWS Methods

Graph-based ensemble methods are able to outperform state-of-the-art template-based reference systems.

Method		GW	PAR	Average
Reference (Template)				
- DTW'01	Geometric (Marti)	45.26	46.78	46.02
- DTW'08	Histogram of Oriented Gradient	63.39	47.52	55.46
- DTW'09	Histogram of Oriented Gradient	64.80	73.49	69.15
- DTW'16	Deep Learning (unsupervised)	68.64	72.38	70.51
Graph (Ensemble)				
- mean-Graph ($n = 2$)		74.62 (1)	80.06 (2)	77.34 (1)
- mean-Graph ($n = 4$)		73.22 (3)	79.79 (3)	76.50 (3)
- mean-Graph ($n = 6$)		69.67	79.11	74.39
- mean-Context ($m = K$)		74.27 (2)	77.36	75.82
- mean-Context ($m = P$)		67.35	78.66	73.00
- mean-All		73.06	81.08 (1)	77.07 (2)

Accuracy is measured by Mean Average Precision

Experiments – Results Graph-based vs. Learning-based KWS Methods

Graph-based ensemble methods are able to keep up with state-of-the-art learning-based reference systems.

Method		BOT		AK		Average
Reference (Learning)						
- SVM	Pyramidal Histogram of Characters	75.77	(2)	77.91		76.84
- CNN (PHOCNet)	Pyramidal Histogram of Characters	89.69	(1)	96.05	(1)	92.87 (1)
- CNN	Discrete Cosine Transform of Words	54.95		82.15		68.55
Graph (Ensemble)						
- mean-Graph ($n = 2$)		71.83		81.52		76.68
- mean-Graph ($n = 4$)		72.43		84.22		78.33 (2)
- mean-Graph ($n = 6$)		69.17		85.20	(3)	77.19
- mean-Context ($m = K$)		72.51	(3)	83.42		77.97
- mean-Context ($m = P$)		67.60		85.46	(2)	76.53
- mean-All		71.67		84.49		78.08 (3)

Accuracy is measured by Mean Average Precision

Conclusion

Graph-based KWS using Context-Aware Hausdorff Edit Distance

improves

Accuracy

(Structural Node Context)

Matching Time

(Quadratic Time Complexity)

Q+A

? !